

# Sensitivity of Change-Point Detection and Trend Estimates to GNSS IWV Time Series Properties

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# Context and objectives

- Study global and regional water cycle in the changing climate
  - Use observations, atmospheric/ocean reanalyses and GCMs
- Ground-based GNSS IWV observations are very accurate with low bias
  - However, even small changes in bias (inhomogeneities) are detrimental to trend and decadal variability analysis
- Inhomogeneities in GNSS data are mainly due to:
  - Equipment changes, changes in the data processing, changes in the environment.
- Reanalyses may also have inhomogeneities, mainly due to:
  - Changes in the global observing system (e.g. start/end of satellite mission)
- Segmentation/homogenization methods help to:
  - Detect and correct inhomogeneities

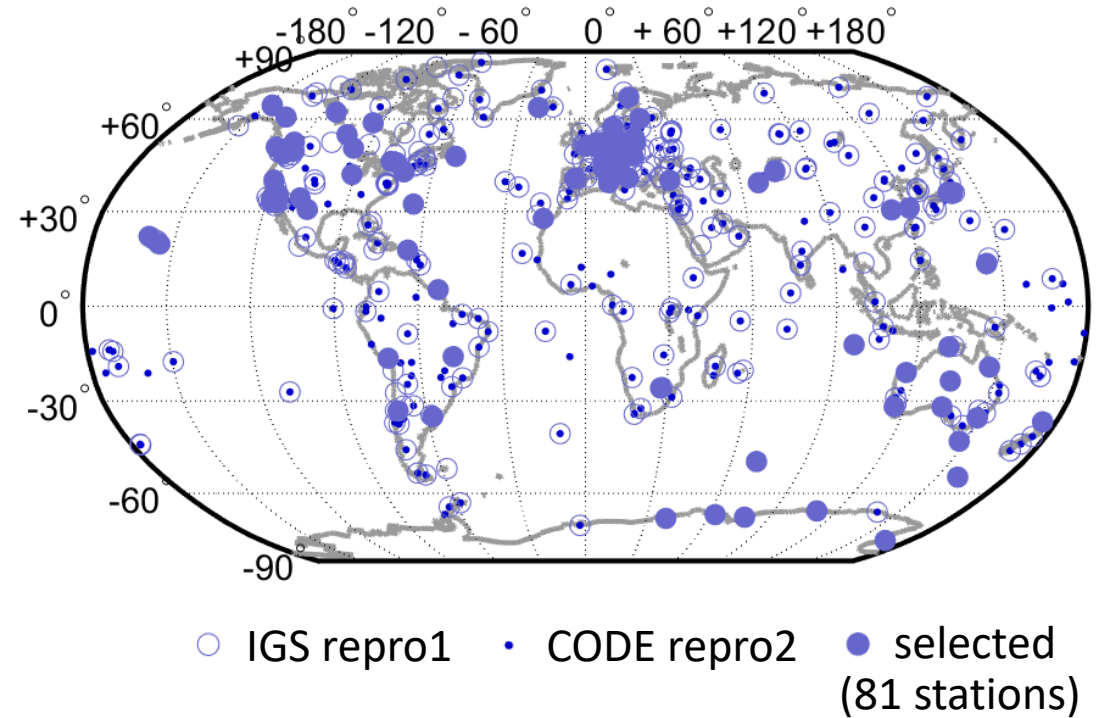
# Context and objectives

- This talk discusses the sensitivity of segmentation results to:
  1. Change in GNSS data set version (repro1 vs. repro2)
  2. Length of time series: 16 years (repro1) vs. 25 years (repro2)
  3. Reference data set used in the target – reference series for the segmentation (reanalyses: ERA-Interim vs. ERA5)
  4. Auxiliary data set used for the conversion of GNSS ZTD data to IWV
- In addition we study the impact of the different segmentation results and data sets on the long-term linear trend estimates

# GNSS data sets (daily IWV times series)

- **IGS repro1**
  - Software: GIPSY OASIS II
  - Released in 2010/2011
  - Covers period 1995-2010
- **CODE (REPRO2015) repro2**
  - Software: Bernese
  - Released in 2015/2019
  - Covers period 1994-2018

(\*) repro2 used more recent satellite products and models => this data set should be more accurate



# Analysis procedure

## (1) GNSS data is ZTD (propag. delay)

- Conversion to IWV needs aux. data

$$IWV = k(T_m) \times \{ ZTD - ZHD(P_s) \}$$

- We use a reanalysis for  $T_m$  and  $P_s$

## (2) Relative homogenization method works on differenced data: target – reference

- We use a reanalysis as reference

## (3) Segmentation method is GNSSseg

- Here we use only the BM1 results

## (4) Outlier screening

- As described in previous talk (E. Lebarbier)

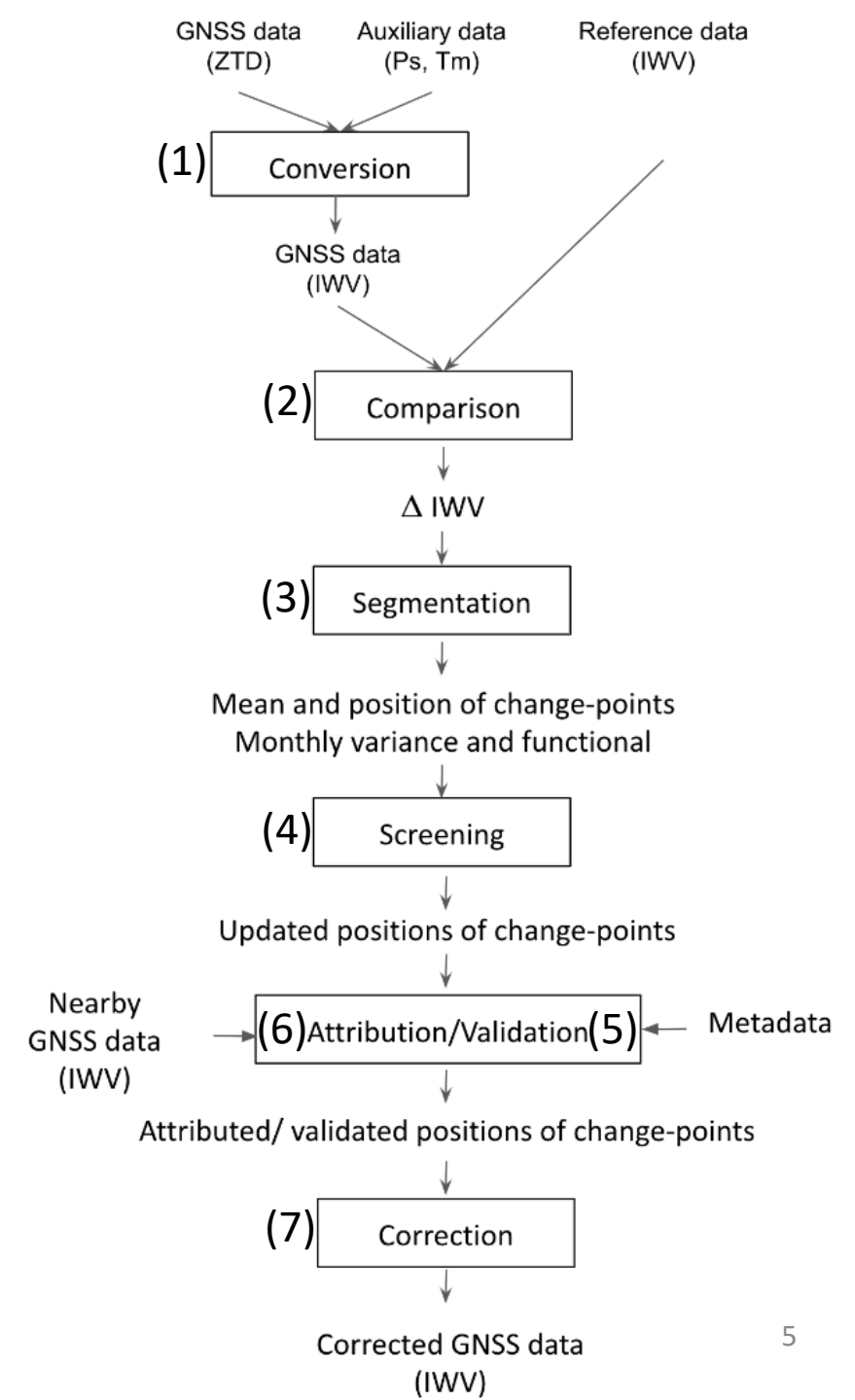
## (5) Validation is done wrt GNSS metadata

- Eq changes are well documented, no relocation issue.

## (6) Attribution is not applied here.

## (7) Correction : piece-wise bias correction, with the most recent segment taken as reference, and using:

- only change-points validated by GNSS metadata,
- all detected change-points (assumed due to GNSS).



# Segmentation results

repro1

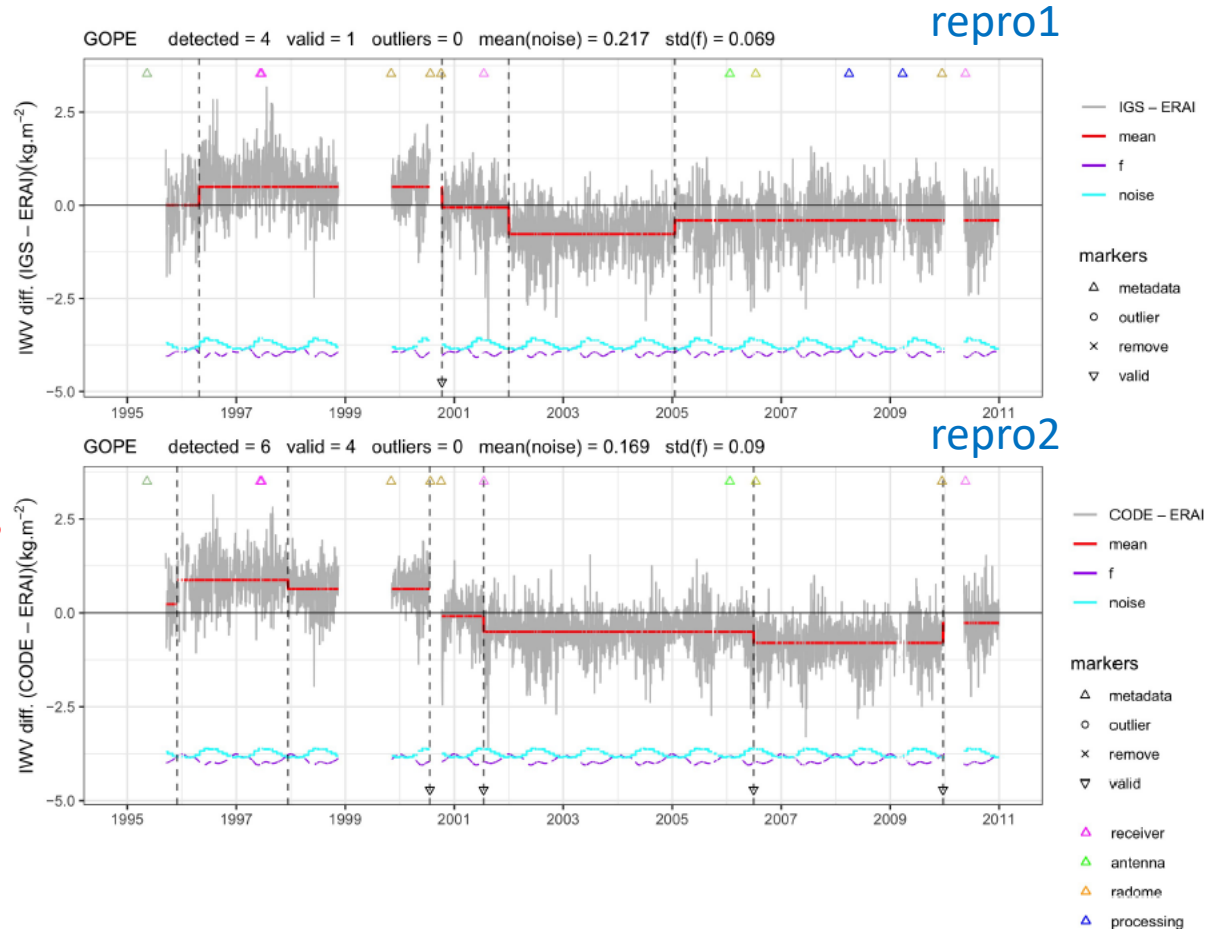
repro2

## (1) Impact of Processing

Data Set	IGS—ERA1 Time-Matched		CODE—ERA1 Time-Matched
Time span	1995–2010		1995–2010
Mean of the monthly variances ( $\text{kg m}^{-2}$ )	0.68	>	0.62
Standard deviation of the functional ( $\text{kg m}^{-2}$ )	0.26	>	0.24
No. detections	231	<	257
No. outliers	36	≈	38
No. detections after screening	211	<	235
Validations after screening	63	<	68
Validations after screening (%)	29.9	≈	28.9
Similar detections	103~48.8%		

less noisy

more detections



repro2 less noisy => higher detection power

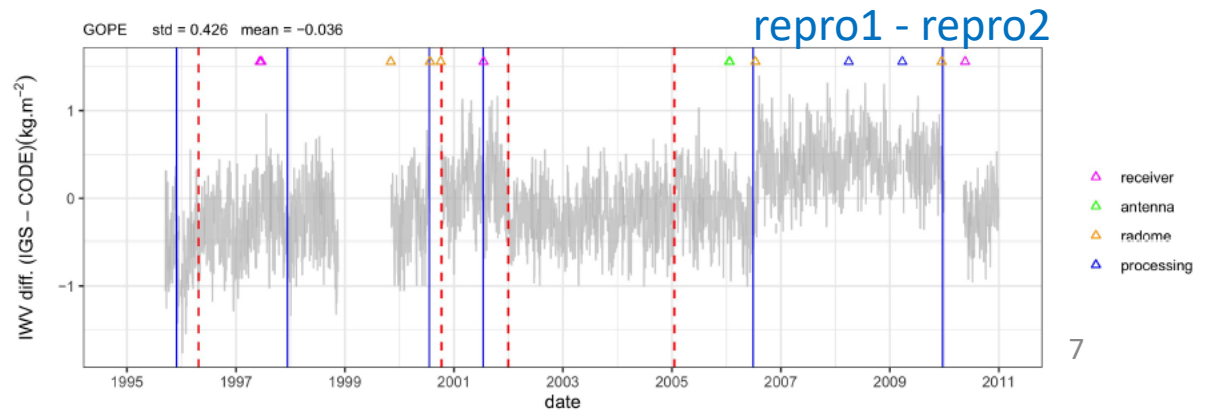
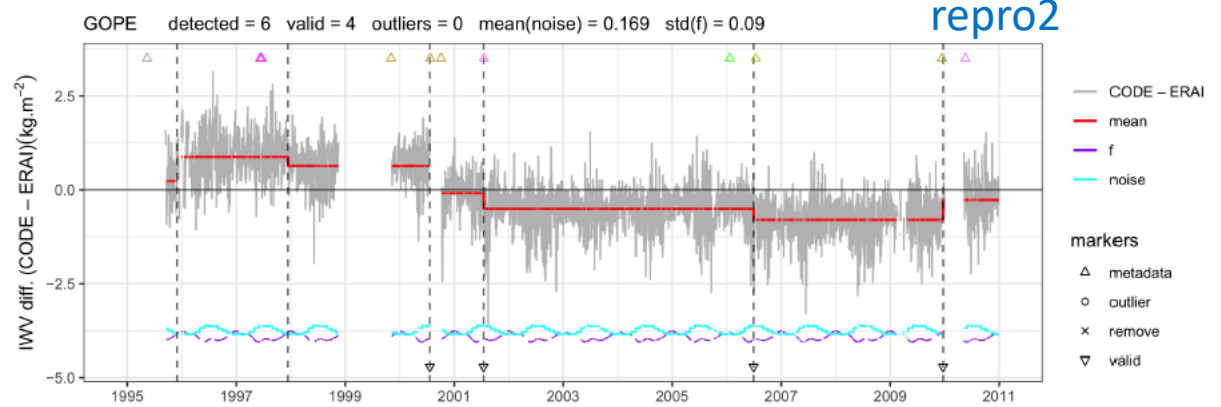
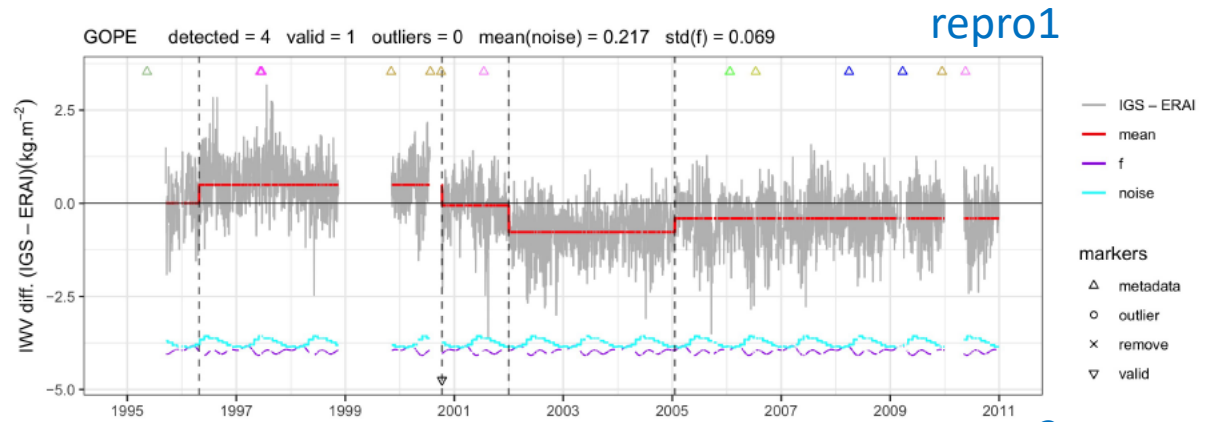
# Segmentation results

repro1

repro2

## (1) Impact of Processing

Data Set	IGS—ERA1 Time-Matched		CODE—ERA1 Time-Matched
Time span	1995–2010		1995–2010
Mean of the monthly variances ( $\text{kg m}^{-2}$ )	0.68	>	0.62
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Similar detections	103~48.8%		



bias between GNSS data sets due to different ant.+rad. models



# Segmentation results

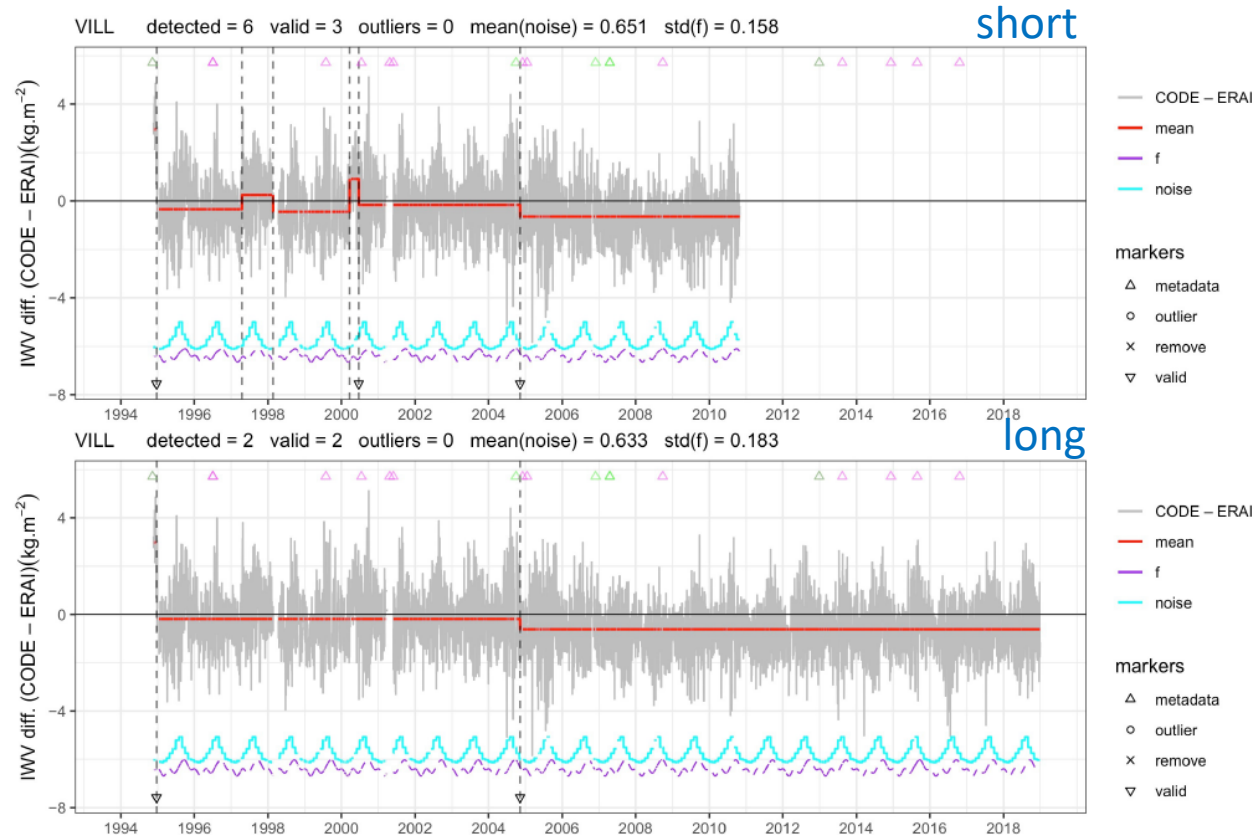
short

long

(2) Impact of Time Length

Data Set	CODE—ERA1 Time-Limited		CODE —ERA1
Time span	1994–2010	<	1994–2018 (a)
Mean of the monthly variances (kg m <sup>-2</sup> )	0.62	≈	0.63
Standard deviation of the functional (kg m <sup>-2</sup> )	0.24	≈	0.23
No. detections	296	>	249 <b>fewer detections</b>
No. outliers	73	>	40
No. detections after screening	252	>	227
Validations after screening	77	≈	78
Validations after screening (%)	30.6	<	34.4 <b>more validations</b>
Similar detections	185~81.5%		

fewer detections on longer period : segmentation is conservative





# Segmentation results

Reference: ERAI

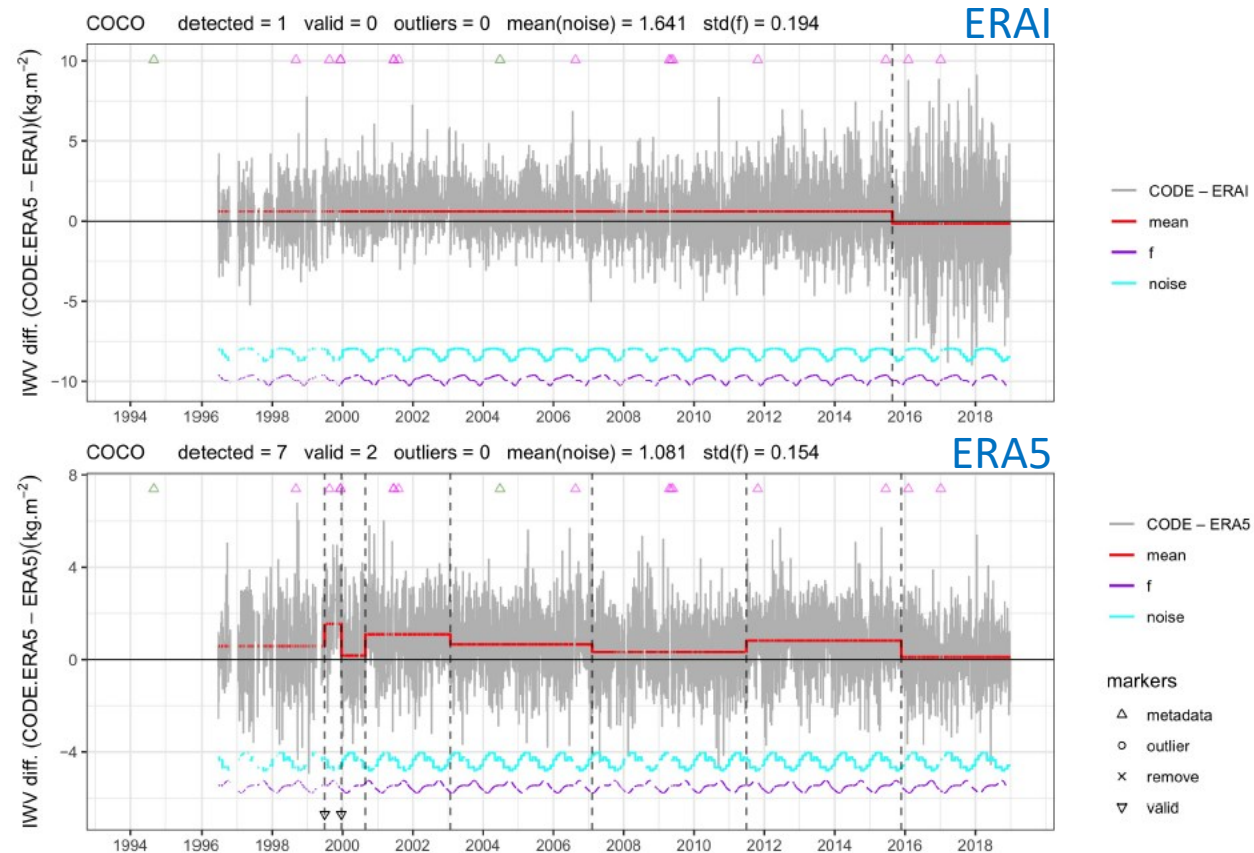
ERA5

(3) Impact of Reference		
Data Set	CODE (b) —ERAI	CODE (b) —ERA5
Time span	1994–2018	1994–2018
Mean of the monthly variances ( $\text{kg m}^{-2}$ )	0.61	> 0.46
Standard deviation of the functional ( $\text{kg m}^{-2}$ )	0.23	> 0.17
No. detections	364	< 398
No. outliers	60	< 71
No. detections after screening	333	< 359
Validations after screening	114	< 131
Validations after screening (%)	34.2	≈ 36.5
Similar detections	151 ~45.3%	

less noisy

more detections

ERA5 less noisy => higher detection power



ERAI more noisy in recent years

# Segmentation results

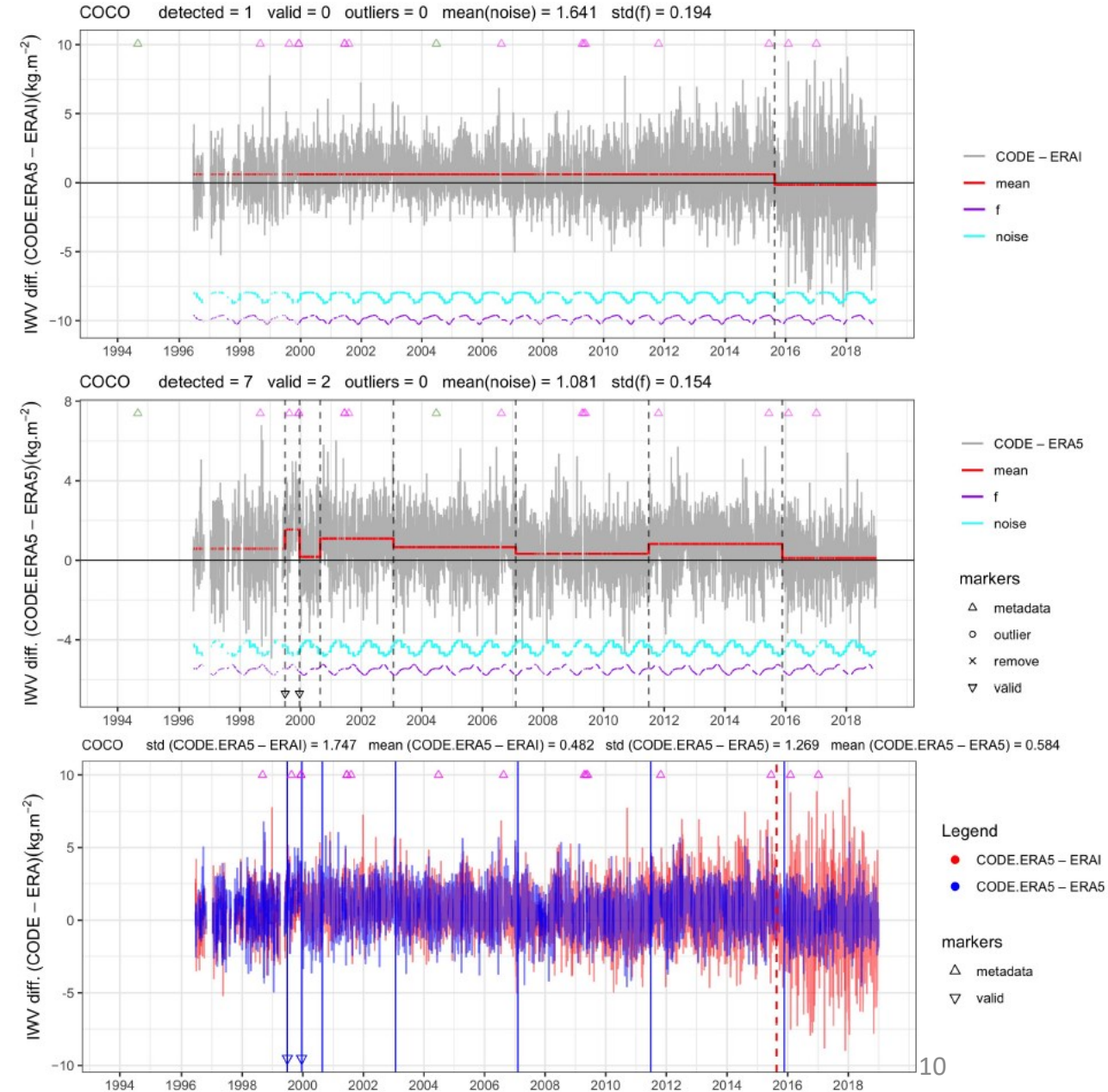
Reference: ERAI

ERA5

### (3) Impact of Reference

Data Set	CODE (b) —ERAI		CODE (b) —ERA5
Time span	1994–2018		1994–2018
Mean of the monthly variances ( $\text{kg m}^{-2}$ )	0.61	>	0.46
Standard deviation of the functional ( $\text{kg m}^{-2}$ )	0.23	>	0.17
No. detections	364	<	398
No. outliers	60	<	71
No. detections after screening	333	<	359
Validations after screening	114	<	131
Validations after screening (%)	34.2	≈	36.5
Similar detections	151 ~45.3%		

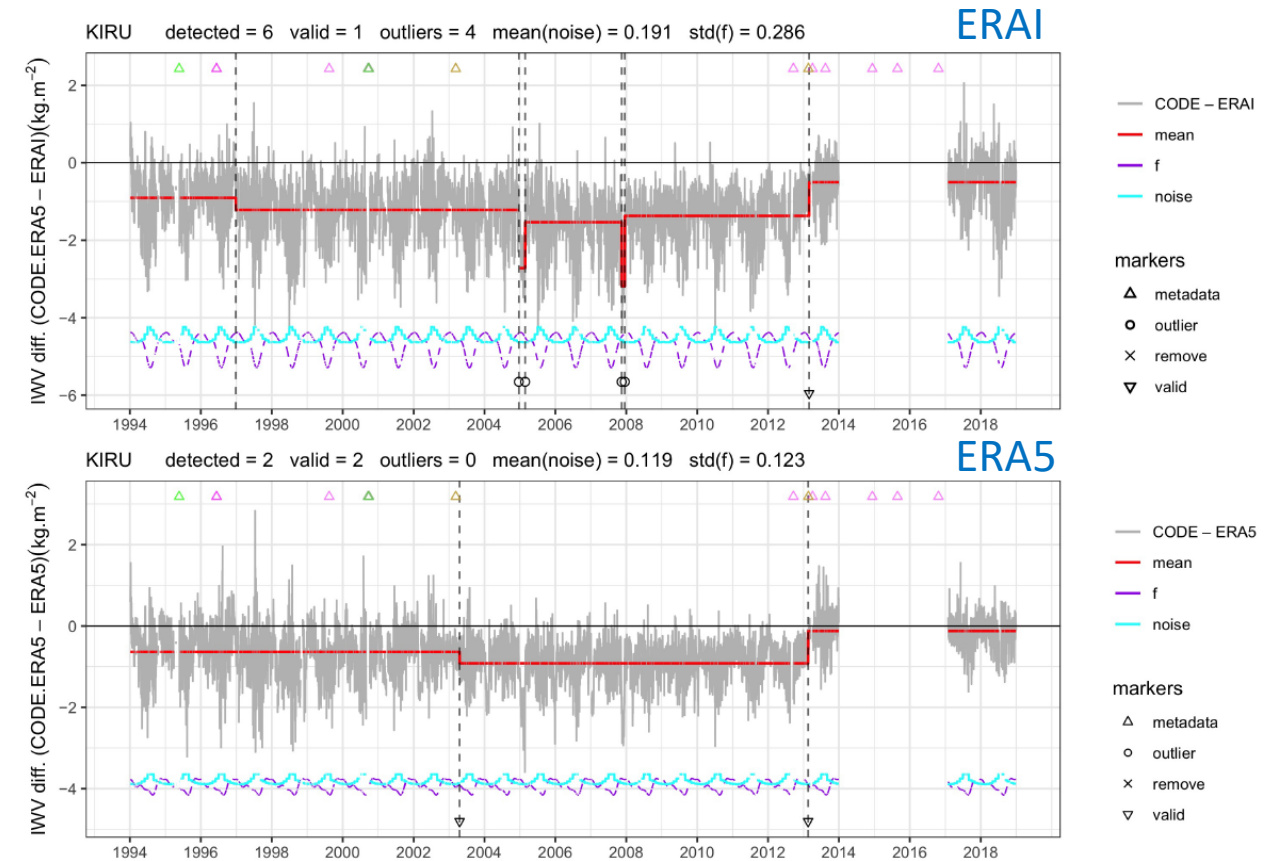
ERA5 less noisy => higher detection power



# Segmentation results

Auxiliary: ERA5 ERAI

(4) Impact of Auxiliary		
Data Set	CODE aux. ERA5	CODE aux. ERAI
Time span	1994–2018	1994–2018
Mean of the monthly variances (kg m <sup>-2</sup> )	0.46	= 0.46
Standard deviation of the functional (kg m <sup>-2</sup> )	0.17	= 0.17
No. detections	398	≈ 392
No. outliers	71	< 87 <b>more outliers</b>
No. detections after screening	359	> 343
Validations after screening	131	> 125
Validations after screening (%)	36.5	≈ 36.4
Similar detections	243 ~70.9%	



ERAI has larger periodic bias (representativeness error)

# Trend estimation procedure

- **Linear Regression Model:**  $y_t = \mu + \omega x_t + s_t + \varepsilon_t$

$y_t$  IWV time series

$x_t$  linear trend function

$\mu$  mean IWV

$\omega$  trend slope

$s_t$  seasonal function : 4th order Fourier Series

$\varepsilon_t$  noise term : AR(1)  $\varepsilon_t = \phi\varepsilon_{t-1} + w_t$

}  $\beta$  coefficients of deterministic model

}  $\phi, \sigma_w^2$  coefficients of stochastic model

- **Estimation method:** Feasible-Generalized Least Squares (FGLS)

$$\left. \begin{array}{l} y = X\beta + \varepsilon \\ \varepsilon \sim N(0, \Sigma_0) \end{array} \right\} \begin{array}{l} \hat{\beta}_{FGLS} = (X' \hat{\Sigma}_n^{-1} X)^{-1} X' \hat{\Sigma}_n^{-1} y \\ Var[\hat{\beta}_{FGLS}] = (X' \hat{\Sigma}_n^{-1} X)^{-1} \end{array} \quad \begin{array}{l} \text{the coefficients of deterministic and stochastic} \\ \text{models are estimated iteratively} \end{array}$$

=>  $\hat{\omega}, \hat{\sigma}_\omega$  trend slope and standard error estimates

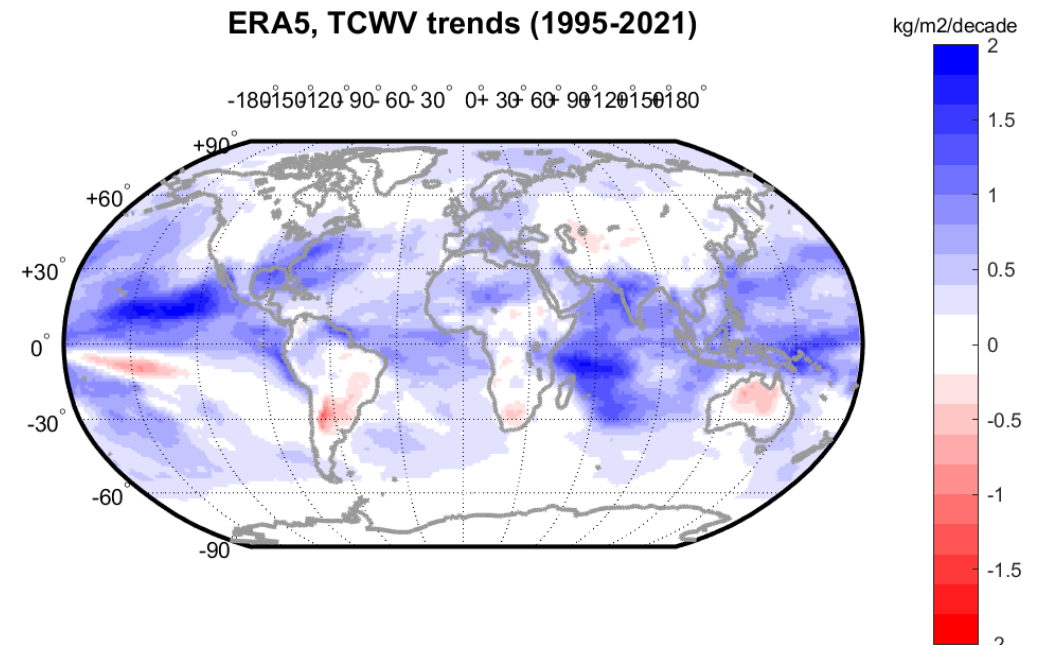
# Trend results: reanalyses

Time Span		1995–2010	1994–2010	1994–2018
Std error ( $\text{kg m}^{-2} \text{ year}^{-1}$ )		0.035	0.033	0.018
ERA-I ( $\text{kg m}^{-2} \text{ year}^{-1}$ )	mean $\pm$ std (signif)	0.018 $\pm$ 0.055 (9)	0.013 $\pm$ 0.049 (10)	0.027 $\pm$ 0.034 (37)
ERA5 ( $\text{kg m}^{-2} \text{ year}^{-1}$ )		0.011 $\pm$ 0.052 (8)	0.008 $\pm$ 0.047 (8)	0.027 $\pm$ 0.031 (35)

(81 stations)

## Increasing length

- **std. error decreases**
- **mean trend (positive) increased in recent years**  
(linked to surface temperature increase  $\approx 7\% / 1\text{K}$ )
- **std. trend (spatial variability) decreases**
- **more significant trends**





# Trend results: raw GNSS vs. reanalyses

Time Span		1995–2010	1994–2010	1994–2018
Std error ( $\text{kg m}^{-2} \text{ year}^{-1}$ )		0.035	0.033	0.018
ERA-I ( $\text{kg m}^{-2} \text{ year}^{-1}$ )		$0.018 \pm 0.055$ (9)	$0.013 \pm 0.049$ (10)	$0.027 \pm 0.034$ (37)
ERA5 ( $\text{kg m}^{-2} \text{ year}^{-1}$ )		$0.011 \pm 0.052$ (8)	$0.008 \pm 0.047$ (8)	$0.027 \pm 0.031$ (35)
GPS		IGS time-matched	CODE time-matched	CODE (c)
Raw data	IWV trend ( $\text{kg m}^{-2} \text{ year}^{-1}$ )	$0.024 \pm 0.059$ (20)	$0.018 \pm 0.060$ (18)	$0.030 \pm 0.031$ (41)
	RMSE wrt ERA5 ( $\text{kg m}^{-2} \text{ year}^{-1}$ )	0.044	0.046	0.033

## IGS vs. CODE

- Stronger trends (positive) in IGS repro1

## GNSS vs. ERA5

- mean : GNSS larger than reanalyses
- std (spatial variability): GNSS larger than reanalyses
- more significant trends
- RMSE (GNSS – ERA5): quite large

} Differences decrease with time

# Trend results: GNSS homogenized (validated)

Time Span		1995–2010	1994–2010	1994–2018	
Std error ( $\text{kg m}^{-2} \text{ year}^{-1}$ )		0.035	0.033	0.018	
ERA1 ( $\text{kg m}^{-2} \text{ year}^{-1}$ )		$0.018 \pm 0.055$ (9)	$0.013 \pm 0.049$ (10)	$0.027 \pm 0.034$ (37)	
ERA5 ( $\text{kg m}^{-2} \text{ year}^{-1}$ )		$0.011 \pm 0.052$ (8)	$0.008 \pm 0.047$ (8)	$0.027 \pm 0.031$ (35)	
	GPS	IGS time-matched	CODE time-matched	CODE time-limited	CODE (c)
Raw data	IWV trend ( $\text{kg m}^{-2} \text{ year}^{-1}$ )	$0.024 \pm 0.059$ (20)	$0.018 \pm 0.060$ (18)	$0.016 \pm 0.060$ (23)	$0.030 \pm 0.031$ (41)
	RMSE wrt ERA5 ( $\text{kg m}^{-2} \text{ year}^{-1}$ )	0.044	0.046	0.046	0.033
corrected IWV by validations	IWV trend ( $\text{kg m}^{-2} \text{ year}^{-1}$ )	$0.015 \pm 0.052$ (12)	$0.014 \pm 0.052$ (11)	$0.011 \pm 0.052$ (15)	$0.027 \pm 0.026$ (34)
	RMSE wrt ERA5 ( $\text{kg m}^{-2} \text{ year}^{-1}$ )	0.038	0.039	0.040	0.019

## GNSS raw vs. homogenized

- mean decreases
- Std (spatial variability) decreases
- Nb significant trends decreases
- RMSE (GNSS – ERA5): decrease

} Homogenized GNSS trends are more similar to reanalyses

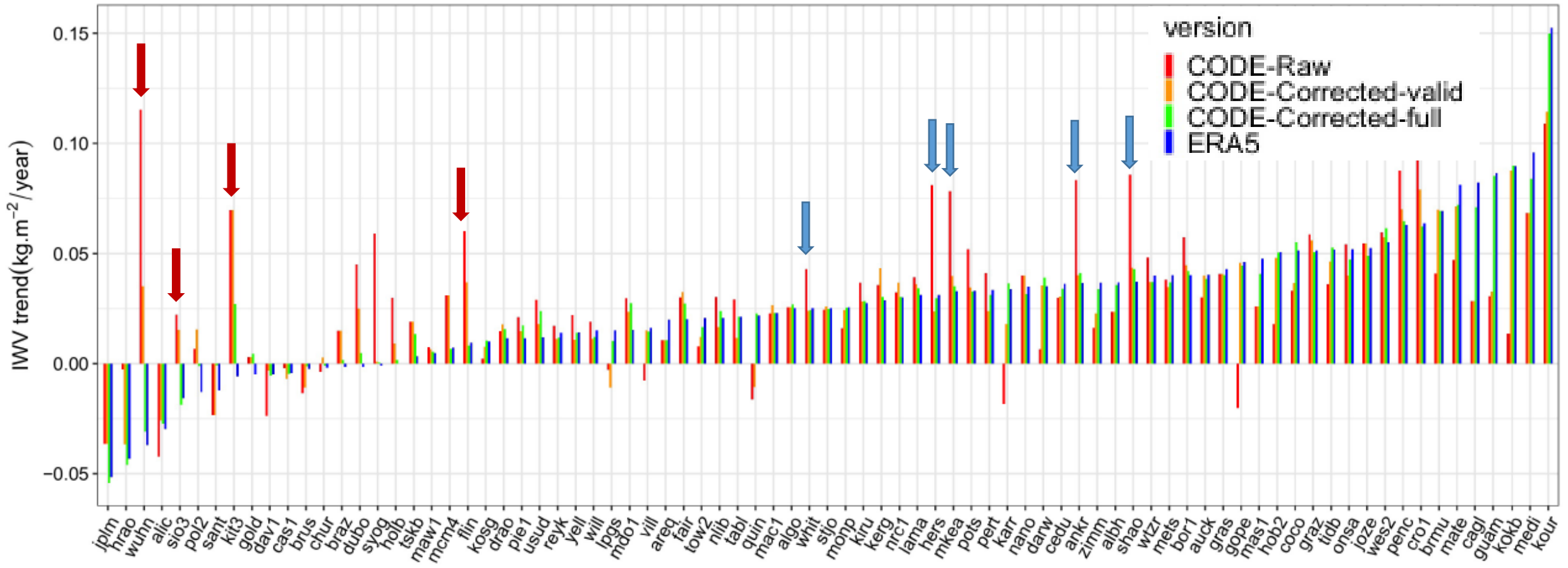


# Trend results: GNSS homogenized (all)

Time Span		1995–2010	1994–2010	1994–2018
Std error ( $\text{kg m}^{-2} \text{ year}^{-1}$ )		0.035	0.033	0.018
ERA1 ( $\text{kg m}^{-2} \text{ year}^{-1}$ )		$0.018 \pm 0.055$ (9)	$0.013 \pm 0.049$ (10)	$0.027 \pm 0.034$ (37)
ERA5 ( $\text{kg m}^{-2} \text{ year}^{-1}$ )		$0.011 \pm 0.052$ (8)	$0.008 \pm 0.047$ (8)	$0.027 \pm 0.031$ (35)
GPS		IGS time-matched	CODE time-matched	CODE time-limited
Raw data	IWV trend ( $\text{kg m}^{-2} \text{ year}^{-1}$ )	$0.024 \pm 0.059$ (20)	$0.018 \pm 0.060$ (18)	$0.016 \pm 0.060$ (23)
	RMSE wrt ERA5 ( $\text{kg m}^{-2} \text{ year}^{-1}$ )	0.044	0.046	0.046
corrected IWV by validations	IWV trend ( $\text{kg m}^{-2} \text{ year}^{-1}$ )	$0.015 \pm 0.052$ (12)	$0.014 \pm 0.052$ (11)	$0.011 \pm 0.052$ (15)
	RMSE wrt ERA5 ( $\text{kg m}^{-2} \text{ year}^{-1}$ )	0.038	0.039	0.040
corrected IWV by all breakpoints	IWV trend ( $\text{kg m}^{-2} \text{ year}^{-1}$ )	$0.017 \pm 0.053$ (9)	$0.016 \pm 0.054$ (9)	$0.012 \pm 0.048$ (13)
	RMSE wrt ERA5 ( $\text{kg m}^{-2} \text{ year}^{-1}$ )	0.021	0.022	0.022

GNSS homogenized with all change-points gets very close to ERA5 (this is expected)

# Trend results: at 81 stations



- In many cases both corrected trends agree with each other and are more consistent with reanalysis
- In some cases the corrected GNSS trends are different and the valided trends don't agree with reanalysis

# Conclusions

- **More recent GNSS data set and reanalysis are less noisy**
  - segmentation has more detection power
    - helps detect biases in GNSS antenna+radome models => next check GNSS repro3
  - only small impact on trend estimates
- **Segmentation is more conservative on longer period**
  - fewer detections (only the most significant offsets are detected)
- **Trend estimates are more precise on longer period**
  - more trends are significant and spatial variability decreases
    - trends increased in recent years (atmosphere gets warmer and moister)
- **Trends from homogenized and validated GNSS data**
  - more similar to ERA5 on average
  - evidence that some changepoints are undocumented or due to reanalysis
    - need a more effective change-point validation strategy => attribution method

# Reference

- Nguyen, K.N.; Quarello, A.; Bock, O., Lebarbier, E. (2021) Sensitivity of Change-Point Detection and Trend Estimates to GNSS IWV Time Series Properties. *Atmosphere*, 12, 1102.  
<https://doi.org/10.3390/atmos12091102>